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Solution for the dynamics of the BCS and central spin problems

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Abstract

We develop an explicit description of a time-dependent response of fermionic condensates to perturbations. The dynamics of Cooper pairs at times shorter than the energy relaxation time can be described by the BCS model. We obtain a general explicit solution for the dynamics of the BCS model. We also solve a closely related dynamical problem—the central spin model, which describes a localized spin coupled to a ‘spin bath’. Here, we focus on presenting the solution and describing its general properties, but also mention some applications, e.g. to nonstationary pairing in cold Fermi gases and to the issue of electron spin decoherence in quantum dots. A typical dynamics of the BCS and central spin models is quasi-periodic with a large number of frequencies and stable under small perturbations. We show that for certain special initial conditions the number of frequencies decreases and the solution simplifies. In particular, periodic solutions correspond to the ground state and excitations of the BCS model.

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1. Introduction

Recent experiments [1] on cold fermion pairing in the vicinity of a Feshbach resonance offer a unique opportunity to control the strength of pairing interactions between fermions by a magnetic field. This opens up an exciting possibility of exploring fundamentally new aspects of the nonequilibrium pairing following an abrupt change of the coupling strength.

Interestingly, the dynamical pairing in this regime can be linked to a seemingly unrelated spin model. The latter describes the interaction of a localized (central) spin with a ‘spin bath’ of environmental spins. The central spin model has re-emerged recently in the context of experiments [2, 3] on electron spin dynamics due to the hyperfine interaction with nuclei in

GaAs quantum dots. Since single electron quantum dots are now experimentally accessible [3], and are considered one of the most promising candidates for solid state qubits, it is also important to understand the effect of this interaction on the coherence of the electron spin.

In this paper, we present a theory that provides an accurate description for a range of phenomena in the dynamical pairing and central spin problems. As we will see below, there is an intimate connection between these two problems that will enable us to treat them on an equal footing.

The study of the dynamics of the superconducting state in metals founded on microscopic principles has begun during the decade following the advent [4] of the BCS theory (see [5] for a review). The simplest theory for nonstationary processes in superconductors is based on the time-dependent Ginzburg–Landau (TDGL) equation [6–8] for the order parameter $\Delta(t)$. The TDGL approach is valid when quasiparticles are able to reach a local equilibrium quickly on the characteristic time scale of the order parameter variation $\tau_\Delta (\simeq \Delta^{-1}$ at zero temperature). This requirement usually limits the applicability of the TDGL theory to situations where mechanisms destroying Cooper pairs are effective, such as a narrow vicinity of T_c or a large concentration of magnetic impurities.

An alternative theory [9, 10] is the Boltzmann kinetic approach, which describes the dynamics in terms of a kinetic equation for the quasiparticle distribution function coupled to a self-consistent equation for $\Delta(t)$. However, this scheme is justified only when external parameters change slowly on the τ_Δ time scale.

As pointed out in [11], cold fermionic gases can be in a regime where the notion of the excitation spectrum is irrelevant and neither TDGL nor the Boltzmann kinetic equations are valid. Indeed, in these systems external parameters such as the detuning from a Feshbach resonance can change on a time scale $\tau_0 \ll \tau_\Delta, \tau_\epsilon$, where τ_ϵ is the quasiparticle energy relaxation time. On the other hand, the energy relaxation is slow, while the lifetime of the samples is limited. It is therefore desirable to develop a theory that describes nonstationary pairing effects in this regime.

The nonequilibrium Cooper pairing at times $t \ll \tau_\epsilon$ is non-dissipative and in a translationally invariant system can be described by the reduced BCS model

$$\hat{H}_{\text{BCS}} = \sum_{\mathbf{p}, \sigma} \epsilon_{\mathbf{p}} \hat{c}_{\mathbf{p}\sigma}^\dagger \hat{c}_{\mathbf{p}\sigma} - g \sum_{\mathbf{p}, \mathbf{k}} \hat{c}_{\mathbf{p}\uparrow}^\dagger \hat{c}_{-\mathbf{p}\downarrow}^\dagger \hat{c}_{-\mathbf{k}\downarrow} \hat{c}_{\mathbf{k}\uparrow}. \quad (1.1)$$

It is interesting to note that the use of this model for describing the dynamics of a homogeneous superconducting state in metals in the non-dissipative regime, $t \ll \tau_\epsilon$, has been justified [12] quite generally starting from nonstationary Eliashberg equations.

Here, we are interested in a situation when a system at zero temperature is out of an equilibrium at $t = 0$. The goal is to determine the subsequent evolution of the initial state. In particular, this includes the case when at $t = 0$ the coupling constant has been abruptly changed from g' to g .

In the absence of translational invariance, e.g. in a dirty superconductor or in a finite system, Hamiltonian (1.1) has to be appropriately generalized [13]. First, let us discuss the familiar case of electron–electron interactions. If there are no spatial symmetries, but the time-reversal invariance is preserved, single-particle orbitals ϵ_j are degenerate only with respect to spin. For each orbital ϵ_j there is a pair of states, $|j \uparrow\rangle$ and $|j \downarrow\rangle$, related by time reversal symmetry. The pairing occurs between time reversed states, i.e.

$$\hat{H}_{\text{BCS}} = \sum_{j, \sigma} \epsilon_j \hat{c}_{j\sigma}^\dagger \hat{c}_{j\sigma} - g \sum_{j, q} \hat{c}_{j\uparrow}^\dagger \hat{c}_{j\downarrow}^\dagger \hat{c}_{q\downarrow} \hat{c}_{q\uparrow}. \quad (1.2)$$

Deviations of the coupling strength g from a constant in q and j are small and sample-dependent [13, 14].

For a two-species Fermi system, such as a two-component mixture of fermionic atoms in a trap, spin up and down states in (1.2) have to be identified with the two species of fermions. With this replacement, arguments [13, 14]⁵ leading to Hamiltonian (1.2) are valid in the weak coupling regime.

Hamiltonian (1.1) is obtained from (1.2) by specializing to a translationally invariant situation. In this case, time reversed states are $|\mathbf{p} \uparrow\rangle$ and $|\mathbf{-p} \downarrow\rangle$. One can also take a thermodynamic limit by taking the number of orbital levels to infinity. However, in view of applications where the effective number of levels is finite and even small (see below), we deal with the general Hamiltonian (1.2) here.

Remarkably, the BCS model turns out to be closely related to a model describing the Heisenberg exchange interaction of a single localized spin (the central spin) with a number of environmental spins. The Hamiltonian reads

$$\hat{H}_0 = \sum_{j=1}^{n-1} \gamma_j \hat{\mathbf{K}}_0 \cdot \hat{\mathbf{K}}_j - B \hat{K}_0^z \quad (1.3)$$

where $\hat{\mathbf{K}}_0$ is the central spin, $\hat{\mathbf{K}}_j$ are environmental spins, γ_j are (nonuniform) coupling constants, and B represents the magnetic field⁶.

The central spin model has an interesting history of its own. For example, it emerged in the studies of electron spin dynamics in disordered insulators [15] and of coherent spin tunnelling in ferromagnetic grains [16]. More recently, it attracted considerable attention as a model for decoherence of qubits [17–20]. In particular, it can be used to model [17, 18] the hyperfine interaction of a localized electron spin with nuclear spins and the spin-dependent transport [21] in GaAs quantum dots. In these cases, it provides an adequate description of spin dynamics at times shorter than the nuclear spin relaxation time in the regime where the orbital level spacing in the dot is much larger than the temperature and typical interaction energies.

The main result of this paper is an explicit general solution for the dynamics of the BCS and central spin models. In particular, we determine as functions of time the order parameter $\Delta(t)$ and the expectation value of the central spin (equations (3.22) and (3.24)) as well as the dynamics of the remaining degrees of freedom for arbitrary initial conditions. Here, we concentrate on presenting the solution and describing its general properties. We also mention several applications to specific issues such as nonequilibrium pairing and that of decoherence due to the hyperfine interaction, but leave a detailed discussion for the future.

The solution is based on the integrability [22–24] of the BCS and central spin models. This important property has been largely underestimated in part because it was discovered outside the main physical context of these models. Besides, due to the infinite range of interactions in Hamiltonians (1.2) and (1.3), the mean field approximation is exact [25, 26] for these models in the limit of large number of particles. In this approximation, the BCS and central spin models can be mapped onto a classical nonlinear system (see below). However, while the mean field simplifies the description of equilibrium properties to an extent where no advanced techniques are required, it is the integrability of the resulting classical system that enables us to solve dynamical problems. The BCS solution [4] for the ground state and excitations of the BCS model is recovered as a periodic case of the general solution (see the discussion following (2.6) and section 4). It is also interesting to note that, as we will see,

⁵ If the trap has certain spatial symmetries, the coupling g in (1.2) can depend on j and q . Hamiltonians (1.2) and (1.1) neglect any such effects, which are usually not important (see also the discussion of stability against perturbations later in the paper).

⁶ Since the component of the total spin along the magnetic field is conserved, including a uniform magnetic field acting on environmental spins is equivalent to adding a constant to the Hamiltonian.

models (1.2) and (1.3), being in many respects classical, have distinct robust features that are preserved when the integrability is destroyed.

The general nonstationary solution of the BCS and central spin models is in terms of hyperelliptic functions—multiple variable generalizations of ordinary elliptic functions. These functions frequently arise as solutions of integrable equations and have well-known analytical properties [27].

We show that for most initial conditions the dynamics is *quasi*-periodic with a number of independent frequencies equal to the number of degrees of freedom, n , and evaluate the frequencies in terms of the integrals of motion. The typical motion uniformly explores an invariant torus—an n -dimensional subspace of the $2n$ -dimensional phase space allowed by the conservation laws. These features of the typical motion are stable against small perturbations that destroy integrability.

Further, we identify certain special values of integrals of motion for which the number of independent frequencies, m , becomes less than the number of degrees of freedom. For these degenerate cases, we were able to explicitly reduce the motion of the BCS and central spin models with n degrees of freedom to that of same systems with only m degrees of freedom. The solution progressively simplifies as the number of independent frequencies decreases. For example, solutions characterized by a single frequency ($m = 1$), i.e. periodic trajectories, are given by trigonometric functions; degenerate solutions with two independent frequencies ($m = 2$) are given by a combination of trigonometric and elliptic functions (see also [11] and the end of section 4), etc.

Periodic solutions ($m = 1$) occupy a special place among degenerate solutions. As we show in section 4, they reproduce the BCS solution for the ground state and excitations of the BCS model.

The paper is organized as follows. In section 2, we use a mean field approximation to map the BCS and central spin models onto equivalent classical models. Section 3 contains an explicit general solution for the dynamics of both problems. In section 4, we consider degenerate solutions. Section 5 discusses some open problems and possible applications of our results.

2. Mean field approximation

Our starting point is the mean field approximation, which enables the mapping of the BCS and central spin models onto equivalent classical nonlinear systems. We also derive the equations of motion and describe the relationship between the BCS and central spin models.

The discussion of the mean field is facilitated by representing BCS Hamiltonian (1.2) in terms of Anderson pseudospin-1/2 operators [25].

$$\hat{H}_{\text{BCS}} = \sum_{j=0}^{n-1} 2\epsilon_j \hat{K}_j^z - g \hat{L}_+ \hat{L}_- \quad \hat{\mathbf{L}} = \sum_{q=0}^{n-1} \hat{\mathbf{K}}_q \quad (2.1)$$

where n is the number of single-particle orbitals. Pseudospin operators are related to fermion creation and annihilation operators via

$$\hat{K}_j^z = \frac{c_{j\uparrow}^\dagger c_{j\uparrow} + c_{j\downarrow}^\dagger c_{j\downarrow} - 1}{2} \quad \hat{K}_j^- = c_{j\downarrow} c_{j\uparrow} \quad \hat{K}_j^+ = c_{j\uparrow}^\dagger c_{j\downarrow}^\dagger. \quad (2.2)$$

Pseudospins are defined on unoccupied and doubly occupied pairs of states $|j \uparrow\rangle$ and $|j \downarrow\rangle$, where they have all properties of spin-1/2. Singly occupied pairs of states, on the other hand, do not participate in pair scattering and are decoupled from the dynamics.

Our goal is to determine the time evolution according to Hamiltonian (2.1) of an arbitrary initial distribution of pseudospins. The mean field approximation consists of the replacement of the effective field seen by each pseudospin in BCS Hamiltonian (2.1) with its quantum-mechanical average, $\mathbf{b}_j(t) = (-2\Delta_x(t), -2\Delta_y(t), 2\epsilon_j)$, where $\Delta(t)$ is the BCS gap function

$$\Delta(t) \equiv \Delta_x(t) - i\Delta_y(t) \equiv g \sum_p \langle \hat{K}_j^-(t) \rangle. \quad (2.3)$$

In this approximation, each spin evolves in the self-consistent field created by other spins

$$\dot{\hat{\mathbf{K}}}_j = i[\hat{H}_{\text{BCS}}, \hat{\mathbf{K}}_j] = \mathbf{b}_j \times \hat{\mathbf{K}}_j. \quad (2.4)$$

Since equations (2.4) are linear in $\hat{\mathbf{K}}_j$, we can take their quantum mechanical average with respect to the time-dependent state of the system to obtain

$$\dot{\mathbf{s}}_j = \mathbf{b}_j \times \mathbf{s}_j \quad \mathbf{b}_j = (-gJ_x, -gJ_y, 2\epsilon_j) \quad \mathbf{J} = \sum_{q=0}^{n-1} \mathbf{s}_q \quad (2.5)$$

where $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$. Evolution equations (2.5) conserve the square of the average for each spin, i.e. $s_j^2 = \text{const}$. If spins initially were in a product state⁷, $s_j^2 = 1$.

Note from equation (2.2) the following correspondence between components of $\mathbf{s}_j(t)$ and the normal and anomalous (Keldysh) Green functions at coinciding times:

$$\begin{aligned} G_j(t) &= -i\langle [c_{j\uparrow}(t), \hat{c}_{j\uparrow}^\dagger(t)] \rangle = is_j^z(t) \\ F_j(t) &= -i\langle [c_{j\uparrow}(t), \hat{c}_{j\downarrow}(t)] \rangle = is_j^-(t). \end{aligned}$$

Equations (2.5) were derived [12] for phonon superconductors within the general framework of nonstationary Eliashberg theory in the collisionless regime $t \ll \tau_c$. A linearized version of these equations was considered in [12, 25, 28, 29].

Due to the infinite range of interactions between spins in (2.1), the mean field approximation is exact in the thermodynamic limit. For a system with a finite number, N , of particles (spins) we expect, based on an analysis of leading finite size corrections [30] to the mean field, equations (2.5) to be accurate for large N at times $t < t^*N^\eta$, where t^* and $\eta > 0$ do not depend on N .

We see that $\mathbf{s}_j = 2\langle \hat{\mathbf{K}}_j \rangle$ have all properties of classical spins governed by a Hamiltonian

$$H_{\text{BCS}} = \sum_{j=0}^{n-1} 2\epsilon_j s_j^z - \frac{g}{2} J_+ J_- \quad (2.6)$$

and usual angular momentum Poisson brackets. Thus, the problem reduces to determining the time evolution of n classical spins according to Hamiltonian (2.6).

The BCS solution for the ground state corresponds to the minimum of (2.6) and is obtained by aligning each spin in (2.6) antiparallel to the field acting upon it. A pair excitation⁸ (excitation of the condensate) of energy $2\sqrt{(\epsilon_j - \mu)^2 + \Delta_0^2}$, where μ and Δ_0 are the chemical potential and the equilibrium gap respectively, is obtained by flipping the spin \mathbf{s}_j . The $U(1)$ symmetry of the BCS order parameter Δ is equivalent to the symmetry of (2.6) with respect to uniform rotations of all spins around the z -axis. Due to this symmetry, spin configurations that determine the ground state and excitations can rotate around the z -axis with a frequency 2μ at no energy cost. In the presence of a particle-hole symmetry $\mu = 0$ and these configurations

⁷ Within the mean field approximation, this is always true in equilibrium with any value of the coupling constant.

⁸ These are excitations that conserve the number of Cooper pairs, see [4, 25].

are stationary with respect to Hamiltonian (2.6) (see section 4 where we recover the BCS solution as a periodic case of the general time-dependent solution).

Next, we turn to the central spin model and its relationship to the BCS model. The central spin Hamiltonian (1.3) turns out to be a member of an integrable family of Gaudin magnets [23]— n Hamiltonians of the form:

$$\hat{H}_q = 2 \sum_{j=0}^{n-1} \frac{\hat{\mathbf{K}}_q \cdot \hat{\mathbf{K}}_j}{\epsilon_q - \epsilon_j} - \alpha \hat{K}_q^z \quad q = 0, \dots, n-1 \quad (2.7)$$

where ϵ_j and α are arbitrary parameters. All Hamiltonians \hat{H}_q commute with each other and with the z -component of the total spin, $\hat{L}_z \propto \sum_q \hat{H}_q$, for arbitrary ϵ_j and α . The central spin model (1.3) coincides with \hat{H}_0 in equation (2.7) if we choose $\epsilon_0 - \epsilon_j = 2/\gamma_j$ and $\alpha = B$.

Note that if a number of orbitals ϵ_j in (2.1) are degenerate, the magnitude of their total spin $\sum_{\epsilon_j=\text{const}} \hat{\mathbf{K}}_j$ is conserved by Hamiltonian (2.1). In this case one can replace $\hat{\mathbf{K}}_j \rightarrow \sum_{\epsilon_j=\text{const}} \hat{\mathbf{K}}_j$ in Hamiltonians (2.1) and (2.7) and sum over nondegenerate orbitals only.

Now consider the following linear combination of \hat{H}_q :

$$\sum_{q=0}^{n-1} \epsilon_q \hat{H}_q = -\frac{\alpha}{2} \left[\sum_{q=0}^{n-1} 2\epsilon_q \hat{K}_q^z - \frac{2}{\alpha} \hat{L}_+ \hat{L}_- \right] + \text{const.}$$

We see that for $\alpha = 2/g$ the expression in the square brackets coincides with BCS Hamiltonian (2.1). Therefore, for $\alpha = 2/g$, the BCS Hamiltonian commutes with all \hat{H}_q and thus belongs to the same class of integrable models [23, 24].

In the same way as we did for the BCS model, we employ the mean field approximation to derive classical Hamiltonians that govern the evolution of $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ for Hamiltonians (2.7):

$$\begin{cases} H_q = \sum_{j=0}^{n-1} \frac{\mathbf{s}_q \cdot \mathbf{s}_j}{\epsilon_q - \epsilon_j} - \alpha s_q^z \\ H_{\text{BCS}} = \sum_{j=0}^{n-1} 2\epsilon_j s_j^z - \frac{J_+ J_-}{\alpha}. \end{cases} \quad (2.8)$$

In particular, the classical counterpart of central spin Hamiltonian (1.3) is

$$H_0 = \sum_{j=0}^{n-1} \frac{\gamma_j}{2} \mathbf{s}_0 \cdot \mathbf{s}_j - B s_0^z. \quad (2.9)$$

The validity of the mean field approximation for central spin model (1.3) is subject to similar considerations as for the BCS model (see the second paragraph following equation (2.5) and also [18]).

Thus, the problem of determining the dynamics of the BCS and central spin models reduces to solving equations of motion for Hamiltonians H_0 and H_{BCS} in system (2.8). To obtain solutions for BCS (1.2) and central spin (1.3) models, one has to choose

$$\begin{aligned} \alpha &= \frac{2}{g} && \text{BCS} \\ \frac{2}{\epsilon_0 - \epsilon_j} &= \gamma_j && \alpha = B \quad \text{central spin.} \end{aligned} \quad (2.10)$$

Hamiltonians (2.8) Poisson commute with each other and with the z -component of the total spin $J_z \propto \sum_q H_q$. Each Hamiltonian in system (2.8) describes an evolution of n spins in an $2n$ -dimensional phase space (two angles for each spin) and has n integrals of motion (the energy and the remaining Hamiltonians from system (2.8)). Therefore, all Hamiltonians (2.8) are classical integrable models.

3. The solution

In the previous section we mapped the BCS and central spin models onto a classical integrable system (2.8). Nevertheless, even though Liouville’s theorem [31] guarantees a formal integrability in quadratures of classical integrable models, an explicit solution for the evolution of the original dynamical variables is not always possible. Fortunately, this turns out to be not the case for the BCS and central spin problems. For these models, as detailed below, we were able to obtain an explicit general solution of equations of motion.

Before we proceed, let us discuss generic features [31] expected of the dynamics of a classical integrable model with n degrees of freedom. The motion is confined by conservation laws to an n -dimensional subspace of the $2n$ -dimensional phase space. This subspace (invariant torus) is determined by initial values of integrals of motion and is topologically equivalent to an n -dimensional torus. The motion on the invariant torus is characterized by n angle variables, ϕ_k and the corresponding angular frequencies, $\phi_k(t) = \Omega_k t + \phi_k(0)$. The frequencies depend only on integrals of motion, while constants $\phi_k(0)$ are determined by initial values of remaining degrees of freedom. Since for most initial conditions all frequencies Ω_k are independent⁹, typical trajectories uniformly explore the entire torus. All these properties are not affected by small perturbations destroying integrability (Kolmogorov–Arnold–Moser theorem).

Now we turn to the solution for the dynamics of the BCS and central spin models. The solution consists of two main steps. The first one is a change of variables that casts equations of motion into the form of a known mathematical problem. In the second step, we use the solution of this problem to obtain dynamical variables $s_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ as explicit functions of time.

The change of variables is facilitated by defining a 2×2 matrix¹⁰ that depends on dynamical variables s_j and also on an auxiliary parameter u

$$\mathcal{L} = \begin{pmatrix} A(u) & B(u) \\ B^*(u) & -A(u) \end{pmatrix} \tag{3.1}$$

where matrix elements of \mathcal{L} are

$$A(u) = \alpha - \sum_{j=0}^{n-1} \frac{s_j^z}{u - \epsilon_j} \quad B(u) = \sum_{j=0}^{n-1} \frac{s_j^-}{u - \epsilon_j}. \tag{3.2}$$

The eigenvalues of this matrix, $\pm v(u)$, depend on dynamical variables only through integrals of motion $-H_j$ and s_j^2

$$v^2(u) = \alpha^2 + \sum_{j=0}^{n-1} \left(\frac{2H_j}{u - \epsilon_j} + \frac{s_j^2}{(u - \epsilon_j)^2} \right) \equiv \frac{\alpha^2 Q_{2n}(u)}{P_n^2(u)} \tag{3.3}$$

where we defined two polynomials, $Q_{2n}(u)$ and $P_n(u)$ that will be frequently used in subsequent calculations

⁹ Frequencies Ω_k are independent if $\mathbf{m} = \mathbf{0}$ is the only vector with integer components such that $\Omega \cdot \mathbf{m} = 0$.

¹⁰ Matrix \mathcal{L} is called the Lax matrix of integrable system (2.8).

$$Q_{2n}(u) \equiv \prod_{j=0}^{2n-1} (u - E_j) \equiv \sum_{k=0}^{2n} \alpha_k u^k \quad \alpha_{2n} = 1 \quad (3.4)$$

$$P_n(u) \equiv \prod_{q=0}^{n-1} (u - \epsilon_q). \quad (3.5)$$

Note that because \mathcal{L} is Hermitian for real u , its eigenvalues are real and therefore the polynomial $Q_{2n}(u)$ is positive definite on the real axis. We will often refer to the polynomial $Q_{2n}(u)$ as the spectral polynomial.

Following an algebraic version of the variable separation method [32, 33], we introduce $n - 1$ variables, u_j , as zeros of $B(u)$ —one of the off-diagonal matrix elements of \mathcal{L} . Variables v_j , canonically conjugate to u_j , are given by one of the eigenvalues of matrix \mathcal{L} at $u = u_j$.

$$B(u_j) = 0 \quad v_j = -A(u_j) \quad j = 1, \dots, n - 1. \quad (3.6)$$

Although we will not use the Hamilton–Jacobi method, we remark that variables (u_j, v_j) separate [33] Hamilton–Jacobi equations for Hamiltonians (2.8). Since u_j are zeros of $B(u)$, we can rewrite the matrix element $B(u)$ as

$$B(u) = J_- \frac{\prod_{j=1}^{n-1} (u - u_j)}{\prod_{j=0}^{n-1} (u - \epsilon_j)} \equiv J_- \frac{R_{n-1}(u)}{P_n(u)}. \quad (3.7)$$

This equation is useful for expressing original dynamical variables—components of spins s_j —through separation variables u_j and J_- . For example, using equations (3.2) and (3.7), we have

$$s_j^- = \operatorname{res}_{u=\epsilon_j} B(u) = J_- \frac{R_{n-1}(\epsilon_j)}{P_n'(\epsilon_j)} \quad (3.8)$$

where the prime denotes a derivative with respect to u .

Equations of motion for central spin Hamiltonian (2.9) in terms of new variables u_j and J_- can be derived by using equation (3.3). We have

$$\begin{aligned} \dot{u}_j &= \frac{iB\sqrt{Q_{2n}(u_j)}}{u_j \prod_{m \neq j} (u_j - u_m)} \frac{s_0^-}{J_-} \\ \dot{J}_- &= iBs_0^- = i\lambda J_- R_{n-1}(0) \quad \lambda = \frac{B}{2^n} \prod_{j=1}^n \gamma_j. \end{aligned} \quad (3.9)$$

Similarly, one obtains equations of motion for BCS Hamiltonian (2.6)

$$\begin{aligned} \dot{u}_j &= \frac{2i\sqrt{Q_{2n}(u_j)}}{\prod_{m \neq j} (u_j - u_m)} \\ \dot{J}_- &= -2iJ_- \left(\sum_{j=0}^{n-1} \epsilon_j + \frac{gJ_z}{2} - \sum_{j=1}^{n-1} u_j \right). \end{aligned} \quad (3.10)$$

In equations (3.9) and (3.10) as well as in the rest of the paper, with no loss of generality, we shifted parameters ϵ_j in the BCS and central spin Hamiltonians by a constant so that $\epsilon_0 = 0$.

In the remainder of this section we obtain an explicit general solution for the expectation value of each (pseudo)spin, $s_j(t) = 2(\hat{\mathbf{K}}_j(t))$, as a function of time. In particular, this includes the expectation value of the central spin, $s_0(t)$, and the BCS gap function, $\Delta(t) = gJ_-(t)$.

The solution is based on the observation that, with the help of elementary algebra, equations of motion (3.9) and (3.10) can be cast into a form of a known mathematical problem. Specifically, one can rewrite equations (3.9) and (3.10) for variables u_j as

$$\sum_{j=1}^{n-1} \frac{u_j^{l-1} du_j}{\sqrt{Q_{2n}(u_j)}} = dx_l \quad l = 1, \dots, n - 1 \tag{3.11}$$

where the polynomial $Q_{2n}(u)$ is defined in equation (3.3). To obtain equations of motion (3.10) for the BCS Hamiltonian one has to choose

$$\mathbf{x}^T = i(c_1, \dots, c_{n-2}, 2t + c_{n-1}) \tag{3.12}$$

while for the central spin model one has

$$\mathbf{x}^T = -i\lambda(t + c_1, \dots, c_{n-2}, c_{n-1}) \tag{3.13}$$

where c_1, \dots, c_{n-1} are arbitrary constants.

Differential equations (3.11) constitute a well-known mathematical problem called Jacobi’s inversion problem (see, for example, [27] and references therein). The solution of equations (3.11) can be expressed [34] through hyperelliptic Abelian functions—multiple variable generalizations of ordinary elliptic functions. These functions are often encountered as solutions of integrable equations and have well-known analytical properties. They are also implemented in standard mathematical software packages [35].

The Riemann theta function of genus g (in our case $g = n - 1$) is defined as the following sum over all g -dimensional integer vectors

$$\theta(\mathbf{x}|\tau) = \sum_{\mathbf{m} \in \mathbb{Z}^g} \exp[i\pi(\mathbf{m}^T \tau \mathbf{m} + 2\mathbf{x}^T \mathbf{m})] \tag{3.14}$$

where $\tau = \omega' \omega^{-1}$, and ω and ω' are $g \times g$ matrices to be specified below. Klenian σ - and ζ -functions of genus g are defined through the Riemann theta function as¹¹

$$\begin{aligned} \sigma(\mathbf{x}) &= C \exp[\mathbf{x}^T \eta (2\omega)^{-1} \mathbf{x}] \theta((2\omega)^{-1} \mathbf{x} | \tau) \\ \zeta_l(\mathbf{x}) &= \frac{\partial \ln \sigma(\mathbf{x})}{\partial x_l}. \end{aligned} \tag{3.15}$$

In our case, the $g \times g$ matrices ω and η (matrices of periods) that appear in the definition of hyperelliptic functions (3.14) and (3.15) are

$$\begin{aligned} 2\omega_{kl} &= \oint_{b_k} \frac{u^{l-1} du}{\sqrt{Q_{2n}(u)}} \\ 2\eta_{kl} &= - \oint_{b_k} \frac{du}{4\sqrt{Q_{2n}(u)}} \sum_{k=l+1}^{2n-1} (k-l)\alpha_{k+l} u^{k-1} \end{aligned} \tag{3.16}$$

where contours of integration b_k go around branch cuts of a hyperelliptic curve $z(u) = \sqrt{Q_{2n}(u)}$ as shown in figure 1. Matrices ω' and η' are also defined by equations (3.16) with the replacement of the contours of integration $b_k \rightarrow h_k$ (see figure 1).

The solution [34] of differential equations (3.11) for arbitrary initial conditions states that functions $u_p(\mathbf{x})$ are zeros of the following polynomial of a degree $g = n - 1$:

$$R_{n-1}(u, t) = u^{n-1} - \sum_{k=1}^{n-1} f_k(\mathbf{x}) u^{k-1} \tag{3.17}$$

¹¹ A more conventional definition of the σ -function is $\sigma(\mathbf{x}) = C \exp[\mathbf{x}^T \eta (2\omega)^{-1} \mathbf{x}] \theta((2\omega)^{-1} \mathbf{x} - \mathbf{r} \tau)$, where \mathbf{r} is a vector of (Riemann) constants. In our case, this makes no difference since the vector \mathbf{r} affects only constants c_k in equations (3.12) and (3.13).

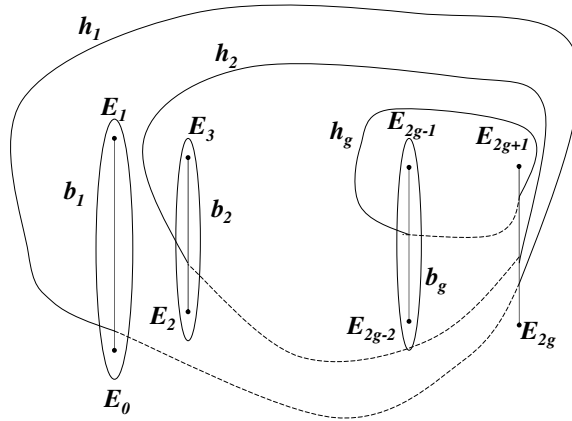


Figure 1. Riemann surface of a hyperelliptic curve $z(u) = \sqrt{Q_{2n}(u)}$ of genus¹² $g = n - 1$ showing contours of integration b_k and h_k with $k = 1, \dots, g$. These contours appear in the definition of matrices of periods (3.16) of hyperelliptic functions. Contours b_k go around $g = n - 1$ branch cuts connecting first $2g = 2n - 2$ roots E_k of the spectral polynomial $Q_{2n}(u)$. Integration along the contours is clockwise. Note that since the spectral polynomial is positively defined the branch cuts are parallel to the imaginary axis.

where coefficients of $R_{n-1}(u, t)$ are

$$f_k(\mathbf{x}) = \zeta_k(\mathbf{x} + \mathbf{d}) - \zeta_k(\mathbf{x} - \mathbf{d}) + a_k. \tag{3.18}$$

Here vector \mathbf{x} is defined by equations (3.12) and (3.13) for the BCS and central spin problems, respectively. The argument of ζ -functions in equations (3.18) is shifted by a vector of constants \mathbf{d} that has the following components:

$$d_l = \int_{E_0}^{\infty} \frac{u^{l-1} du}{\sqrt{Q_{2n}(u)}} \quad l = 1, \dots, n - 1 \tag{3.19}$$

where E_0 is one of the roots of the spectral polynomial $Q_{2n}(u)$ (see figure 1 and equation (3.4)). Note that, according to its definition (3.3), the spectral polynomial $Q_{2n}(u)$ depends only on integrals of motion and on parameters ϵ_j and α .

Finally, constants a_k in equations (3.18) are obtained from the expansion

$$\sqrt{\sum_{k=0}^{2n} \frac{\alpha_k}{z^k}} = \frac{1}{z^n} + \frac{a_1}{z^{n-1}} + \dots + \frac{a_{n-1}}{z} + O(1) \tag{3.20}$$

where α_k are the coefficients of the spectral polynomial $Q_{2n}(u)$ defined by equation (3.4). For example, $a_{n-1} = \alpha_{2n-1}/2$, $a_{n-2} = \alpha_{2n-2}/2 - \alpha_{2n-1}^2/8$, etc.

To obtain quantum mechanical expectation values of original spins $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ for central spin model (1.3) and pseudospins (2.2) for BCS model (1.2), we observe that, according to equation (3.8), they can be expressed through the polynomial $R_{n-1}(u, t)$ given by expression (3.17). We have

$$s_j^-(t) = J_-(t) \frac{R_{n-1}(\epsilon_j, t)}{P'_n(\epsilon_j)}. \tag{3.21}$$

¹² The genus is the number of handles on the Riemann surface of $z(u) = \sqrt{Q_{2n}(u)}$. The latter consists of two branches glued along n cuts (see figure 1). Each branch is a complex plane that is equivalent to a sphere. Because the two spheres are glued along n cuts, there are $g = n - 1$ handles.

Recall that coefficients of the polynomial $P_n(u)$, defined by equation (3.5), depend only on parameters ϵ_j .

Similarly, one can use an expression for the matrix element $A(u)$ defined in equation (3.2) in terms of variables u_j to obtain z -components of (pseudo)spins as functions of time. However, these components are not independent and can also be obtained from the equation $(s_j^z)^2 + |s_j^-|^2 = s_j^2 = 1$, where the sign of s_j^z is determined by initial conditions.

Integrating equations (3.9) and (3.10) for the evolution of x and y components of the total (pseudo)spin with the help of equation (3.18), we obtain

$$J_-(t) = c_n e^{-i\beta t} \frac{\sigma(\mathbf{x} + \mathbf{d})}{\sigma(\mathbf{x} - \mathbf{d})} \quad \Delta(t) = g J_-(t) \tag{3.22}$$

where the vector \mathbf{x} is defined by equations ((3.12)) and ((3.13)). The frequency β is different for the BCS (β_{BCS}) and central spin (β_0) models

$$\beta_{\text{BCS}} = \frac{gJ_z}{2} + \sum_{j=0}^{n-1} \epsilon_j \quad \beta_0 = a_1 \lambda, \tag{3.23}$$

where λ and a_1 are defined in equations (3.9) and (3.20) respectively.

Average components of the electron (central) spin, $\mathbf{s}_0(t) = 2\langle \mathbf{K}_0(t) \rangle$ are obtained from equation (3.21) (recall that $\epsilon_0 = 0$)

$$s_0^-(t) = c'_n [\zeta_1(\mathbf{x} - \mathbf{d}) - \zeta_1(\mathbf{x} + \mathbf{d}) - a_1] \frac{\sigma(\mathbf{x} + \mathbf{d})}{\sigma(\mathbf{x} - \mathbf{d})} \tag{3.24}$$

where $c'_n = (\lambda c_n)/B$.

To summarize, quantum-mechanical averages of (pseudo)spins for the BCS and central spin models, including the electron (central) spin and the BCS gap function $\Delta(t)$ are hyperelliptic functions (equations (3.14) and (3.15)) of the time variable and $n - 1$ constants c_k (equations (3.21), (3.22) and (3.24)). These functions are specified by their matrices of periods ω, ω' and η . The latter depend only on integrals of motion according to equations (3.3) and (3.16). The remaining n out of $2n$ initial conditions fix constants c_k in equations (3.12) and (3.13).

An important characteristic of a quasi-periodic motion is its (Fourier) frequencies. To determine the frequencies for the BCS and central spin models, we observe from equation (3.15) that the time variable enters the solution through combinations of $e^{i\Omega_k t}$, where

$$\begin{aligned} \Omega_k &= i\pi \omega_{kg}^{-1} && \text{BCS} \\ \Omega_k &= -i\pi \omega_{k1}^{-1} && \text{central spin} \end{aligned} \tag{3.25}$$

$k = 1, \dots, g$, and $g = n - 1$. Note that, since the spectral polynomial $Q_{2n}(u)$ in equation (3.16) is positively defined, the matrix ω is pure imaginary and, therefore, frequencies Ω_k are real¹³ (see figure 1).

4. Degenerate solutions

Here we identify a class of ‘resonant’ nonstationary solutions for the BCS and central spin models with n degrees of freedom (n spins or pseudospins) but only $m < n$ independent frequencies.

While a typical dynamics of the BCS and central spin models with n (pseudo)spins is quasi-periodic with n independent frequencies, it is clear already on physical grounds that there

¹³ In addition to $n - 1$ frequencies Ω_k there is one more frequency that comes from the exponential prefactor in the σ -function (3.15). We were not able to find a simple expression for this frequency.

must be solutions with fewer frequencies. For example, the only ‘spatial’ symmetry of the BCS ground state is the $U(1)$ symmetry of the order parameter that translates into rotations of all pseudospins in Hamiltonians (2.1) and (2.6) around the z -axis. The corresponding trajectory in the phase space is a circle and, therefore, the motion is periodic with a single frequency (see also the discussion following equation (2.6) and below in this section).

Generally, one can show [31] that there are (resonant) tori with an arbitrary number $m < n$ of independent frequencies in a vicinity of any point in the phase space. It should be noted though that the set of points for which $m < n$ has a zero measure in the phase space just like the set of rational numbers on the real axis. Moreover, such points are typically unstable [31] and provide seeds of chaotic behaviour in integrable systems. This occurs because small perturbations can destroy resonant tori and let the corresponding trajectories escape to other regions of the energy shell. In contrast, the majority of invariant tori with n independent frequencies are only slightly deformed by perturbations.

Interestingly, for the resonant (degenerate) cases considered here we were able to reduce the BCS and central spin models with n spins to same models with only m spins. For example, solutions with $m = 2$ frequencies can be obtained from the BCS and central spin models for only two spins, etc. Further, we will see that one spin solutions (periodic trajectories) are special among degenerate solutions in that they correspond to the BCS energy spectrum.

We start by determining conditions under which the number of independent frequencies is reduced. Since the frequencies are fixed by initial values of integrals of motion, degeneracies occur only for special values of the integrals. On the other hand, a complete information about integrals of motion is encoded in the spectral polynomial $Q_{2n}(u)$ defined in equations (3.3) and (3.4). Specifically, we have seen in the previous section that the number of frequencies Ω_k is equal to the number of branch cuts of the hyperelliptic curve $z(u) = \sqrt{Q_{2n}(u)}$. Evidently, the latter decreases by one when two roots of the polynomial $Q_{2n}(u)$ coincide. Thus, as detailed below, merging $2(n - m)$ roots of $Q_{2n}(u)$ we obtain solutions with $m < n$ frequencies.

Indeed, consider a situation when $2(n - m)$ roots coincide, i.e. the spectral polynomial $Q_{2n}(u)$ in equation (3.3) has the following special form:

$$Q_{2n}(u) = \tilde{Q}_{2m}(u) \prod_{k=m}^{n-1} (u - E_k)^2 = \tilde{Q}_{2m}(u) W_{n-m}^2(u). \quad (4.1)$$

We assume that double roots in equation (4.1) are complex conjugate to each other so that coefficients of polynomials $\tilde{Q}_{2m}(u)$ and $W_{n-m}(u)$ are real. Note that, since the polynomial $Q_{2n}(u)$ is positively defined (see the remark following equation (3.5)), so is the polynomial $\tilde{Q}_{2m}(u)$. We will see below that degenerate solutions are completely determined by the ‘residual’ spectral polynomial $\tilde{Q}_{2m}(u)$.

Now let us choose $m - n$ separation variables u_j to coincide with double roots of the polynomial $Q_{2n}(u)$, i.e.

$$u_j = E_j \quad j = m, \dots, n - 1$$

$$W_{n-m}(u) = \prod_{k=m}^{n-1} (u - E_k) = \prod_{j=m}^{n-1} (u - u_j). \quad (4.2)$$

We observe that equations of motion for these variables are automatically satisfied because both sides of equations (3.9) and (3.10) vanish.

Next, we use equations (4.1) and (3.3) to express eigenvalues of matrix \mathcal{L} in terms of the residual spectral polynomial $\tilde{Q}_{2m}(u)$ as follows,

$$v^2(u) = \alpha^2 \left(\sum_{q=0}^{n-1} \frac{C_q}{u - \epsilon_q} \right)^2 \tilde{Q}_{2m}(u) \tag{4.3}$$

where we expanded the ratio of polynomials $W_{n-m}(u)$ and $P_n(u)$ into elementary fractions

$$\frac{W_{n-m}(u)}{P_n(u)} = \sum_{q=0}^{n-1} \frac{C_q}{u - \epsilon_q}. \tag{4.4}$$

Since the degrees of polynomials $W_{n-m}(u)$ and $P_n(u)$ differ by m , there are m constraints on the values of C_q , which can be derived by expanding equation (4.4) in $1/u$. We have

$$\sum_{q=0}^{n-1} C_q \epsilon_q^{k-1} = \delta_{km} \quad k = 1, \dots, m. \tag{4.5}$$

Values of C_q can be expressed through coefficients of $\tilde{Q}_{2m}(u)$ by comparing residues at double poles at $u = \epsilon_q$ in equations (3.3) and (4.3),

$$C_q = \frac{e_q}{\alpha \sqrt{\tilde{Q}_{2m}(\epsilon_q)}} \quad \text{where } e_q = \pm 1. \tag{4.6}$$

Note that equations (4.5) provide the following m constraints,

$$\sum_{q=0}^{n-1} \frac{e_q \epsilon_q^{k-1}}{\sqrt{\tilde{Q}_{2m}(\epsilon_q)}} = \alpha \delta_{km} \quad k = 1, \dots, m \tag{4.7}$$

on $2m$ coefficients of a positively defined polynomial $\tilde{Q}_{2m}(u)$.

Values of integrals of motion H_q for which degeneracies occur can be determined in terms of coefficients of the residual spectral polynomial $\tilde{Q}_{2m}(u)$ by comparing residues at simple poles at $u = \epsilon_q$ in equations (3.3) and (4.3).

$$H_q = \alpha^2 \sum_{j=0}^{n-1} \frac{C_q C_j \tilde{Q}_{2m}(\epsilon_q)}{\epsilon_q - \epsilon_j} + \frac{\alpha^2}{2} C_q^2 \tilde{Q}'_{2m}(\epsilon_q). \tag{4.8}$$

In particular, the value of H_0 —twice the energy¹⁴ of the central spin model on degenerate solutions is

$$\mathcal{E}_0 = h \sqrt{\tilde{\alpha}_0} e_0 \sum_{q=1}^{n-1} \frac{C_j \gamma_j}{4} + \frac{\tilde{\alpha}_1}{2 \tilde{\alpha}_0} \tag{4.9}$$

where $\tilde{\alpha}_k$ are coefficients of $\tilde{Q}_{2m}(u)$ defined as

$$\tilde{Q}_{2m}(u) \equiv \sum_{k=0}^{2m} \tilde{\alpha}_k u^k \quad \tilde{\alpha}_{2m} = 1. \tag{4.10}$$

The BCS energy $\mathcal{E}_{\text{BCS}} \propto \sum_q \epsilon_q H_q + \text{const}$ and the value of $J_z \propto \sum_q H_q$ can be obtained from the knowledge of H_q . However, a more convenient derivation is to compare expansions of equations (3.3) and (4.3) in powers of $1/u$. We have

¹⁴ The factor of two arises because with the choice $\mathbf{s}_p = 2(\hat{\mathbf{K}}_p)$ the value of classical Hamiltonians (2.6) and (2.9) is twice the value of their quantum counterparts (2.1) and (1.3).

$$J_z + \alpha \sum_{q=0}^{n-1} C_q \epsilon_q^m = -\frac{\alpha \tilde{\alpha}_{2m-1}}{2} \quad (4.11)$$

$$g\mathcal{E}_{\text{BCS}} = -\sum_{q=0}^{m-1} C_q (2\epsilon_q^{m+1} + \tilde{\alpha}_{2m-1}\epsilon_q^m) - \frac{\tilde{\alpha}_{2m-1}^2}{4} + \tilde{\alpha}_{2m-2}. \quad (4.12)$$

So far, we determined initial conditions for which the number of independent frequencies for a system with n (pseudo)spins drops from n to m . We saw that these conditions are fixed by the residual spectral polynomial $\tilde{Q}_{2m}(u)$. Note that separation variables u_j with $j \geq m$ are also fixed by this polynomial because they are zeros of equation (4.4).

Thus, we are left with m dynamical variables— u_j with $j = 1, \dots, m-1$ and J_- . Equations of motion (3.9) and (3.10) for these u_j can be cast into a standard form (3.11) where n is now replaced with m and the original spectral polynomial $Q_{2n}(u)$ is replaced with the residual polynomial $\tilde{Q}_{2m}(u)$. On the other hand, it is clear that we would obtain similar equations of motion for m spins $\tilde{\mathfrak{s}}_j$ governed by the BCS or central spin Hamiltonians. This analogy can be made precise if we identify the residual polynomial $\tilde{Q}_{2m}(u)$ with the spectral polynomial of a system of m spins (cf equation (3.3)), i.e.

$$\tilde{v}^2 = \alpha^2 + \sum_{j=0}^{m-1} \left(\frac{2\tilde{H}_j}{u - \tilde{\epsilon}_j} + \frac{\tilde{\mathfrak{s}}_j^2}{(u - \tilde{\epsilon}_j)^2} \right) = \frac{\alpha^2 \tilde{Q}_{2m}(u)}{\tilde{P}_m^2(u)} \quad (4.13)$$

where we replaced parameters ϵ_j with new ones

$$\tilde{P}_m(u) = \prod_{q=0}^{m-1} (u - \tilde{\epsilon}_q) \quad (4.14)$$

and chose $\tilde{\epsilon}_0 = 0$, consistent with the choice $\epsilon_0 = 0$ (see below equation (3.10)). The rest of $\tilde{\epsilon}_j$ are arbitrary real numbers.

BCS (2.6) and central spin (2.9) Hamiltonians for new classical spins $\tilde{\mathfrak{s}}_j$ are

$$\begin{aligned} \tilde{H}_{\text{BCS}} &= \sum_{j=0}^{m-1} 2\tilde{\epsilon}_j \tilde{\mathfrak{s}}_j^z - \frac{g}{2} \tilde{J}_+ \tilde{J}_- & \tilde{\mathbf{J}} &= \sum_{q=0}^{m-1} \tilde{\mathfrak{s}}_q \\ \tilde{H}_0 &= \sum_{j=0}^{m-1} \frac{\tilde{\gamma}_j}{2} \tilde{\mathfrak{s}}_0 \cdot \tilde{\mathfrak{s}}_j - B\tilde{\mathfrak{s}}_0^z & \tilde{\gamma}_j &= \frac{2}{\tilde{\epsilon}_0 - \tilde{\epsilon}_j}. \end{aligned} \quad (4.15)$$

Now, comparing equations of motion (3.9) and (3.10) for m separation variables \tilde{u}_j for new spins with those for the remaining variables u_j for $j = 1, \dots, m-1$ in the original problem with n spins, we see that they coincide if we re-scale the time variable for the central spin problem as follows:

$$\begin{aligned} \tilde{t} &= \frac{(-1)^n e_0 \prod_{k=1}^{m-1} \tilde{\epsilon}_m}{B\sqrt{\alpha_0}} t & \text{central spin} \\ \tilde{t} &= t & \text{BCS.} \end{aligned} \quad (4.16)$$

No re-scaling is necessary for the BCS model. Further, analysing equations of motion for x and y components of the total spin (3.9) and (3.10), we conclude that they coincide for original and new spins, i.e.

$$\tilde{J}_- = J_-.$$

To express original n (pseudo)spins $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ in terms of m new spins $\tilde{\mathbf{s}}_j(\tilde{t})$, we use equations (4.4) and (4.2) to rewrite the matrix element $B(u)$ given by equation (3.7) as

$$\begin{aligned} B(u) &= J_- \prod_{j=1}^{m-1} (u - u_j) \sum_{q=0}^{n-1} \frac{C_q}{u - \epsilon_q} \\ &= \tilde{B}(u) \tilde{P}_m(u) \sum_{q=0}^{n-1} \frac{C_q}{u - \epsilon_q}. \end{aligned} \tag{4.17}$$

Evaluating residues at $u = \epsilon_j$ in equation (4.17), we obtain according to equation (3.8)

$$s_j^-(t) = C_j \tilde{P}_m(\epsilon_j) \sum_{q=0}^{m-1} \frac{\tilde{s}_j^-(\tilde{t})}{\epsilon_j - \tilde{\epsilon}_q} \tag{4.18}$$

where constants C_j are given by equation (4.6). Similarly, one can relate z -components of original spins to new ones

$$s_j^z(t) = C_j \tilde{P}_m(\epsilon_j) \left(-\alpha + \sum_{q=0}^{m-1} \frac{\tilde{s}_j^z(\tilde{t})}{\epsilon_j - \tilde{\epsilon}_q} \right). \tag{4.19}$$

The solution for new spins $\tilde{\mathbf{s}}_j(\tilde{t})$ as functions of time can be read off directly from the general solution—equations (3.21), (3.22) and (3.24) of the previous section. We only need to replace n with m , re-scale the time variable for the central spin model according to equation (4.16), and replace the spectral polynomial $Q_{2n}(u)$ with its reduced counterpart $\tilde{Q}_{2m}(u)$ in the definition of matrices of periods (3.16) of hyperelliptic functions.

For future reference, let us also write equations for components of original spins $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ and evolution of $J_-(t)$ for degenerate solutions in terms of m variables $\tilde{u}_j = u_j$. Evaluating residues at $u = \epsilon_j$ in equation (4.17) and using equation (3.8), we find

$$s_j^- = C_j J_- \prod_{j=1}^{m-1} (\epsilon_j - u_j). \tag{4.20}$$

With the help of equations (4.1) and (4.20), evolution equations (3.9) and (3.10) for J_- become

$$\begin{aligned} \frac{d \ln J_-}{dt} &= \frac{(-1)^m i e_0}{\sqrt{\alpha_0}} \prod_{j=1}^{m-1} u_j && \text{central spin} \\ \frac{d \ln J_-}{dt} &= i \left(\tilde{\alpha}_{2m-1} + 2 \sum_{j=1}^{m-1} u_j \right) && \text{BCS.} \end{aligned} \tag{4.21}$$

We see that degenerate solutions with $m < n$ frequencies can be parametrized by m auxiliary spins both for the BCS and central spin model. Therefore, corresponding trajectories live on an m -dimensional torus. By symmetry, for the same initial conditions, trajectories of all Hamiltonians H_q in system (2.8) live on the same torus. This implies, for example, that a slight change of initial values of integrals of motion (4.8) will induce small oscillations along the remaining $n - m$ directions.

Let us consider several examples of degenerate solutions.

One-spin solutions, $m = 1$. These solutions reproduce the BCS solution for the ground state and excitations of the BCS model (see also the discussion following equation (2.6)).

Since the residual spectral polynomial is positively defined, we can parametrize it as $\tilde{Q}_2(u) = (u - \mu)^2 + \Delta_0^2$. For $m = 1$, there is only one condition in equation (4.7)

$$\sum_{q=0}^{n-1} \frac{e_q}{\sqrt{(\epsilon_q - \mu)^2 + \Delta_0^2}} = \alpha \quad e_q = \pm 1. \quad (4.22)$$

For the BCS model $\alpha = 2/g$ and we recognize equation (4.22) as the BCS gap equation. Similarly, equation (4.11) becomes the BCS equation for the chemical potential.

The energy of BCS model (4.12) for $m = 1$ is

$$\mathcal{E}_{\text{BCS}} = \frac{\Delta_0^2}{g} - \mu J_z - \sum_{j=0}^{n-1} e_j \sqrt{(\epsilon_j - \mu)^2 + \Delta_0^2}. \quad (4.23)$$

We see that a choice of signs $e_j = 1$ for all j yields the BCS ground state energy, while if we choose one of e_j to be negative, $e_q = -1$ and $e_j = 1$ for $j \neq q$, the solution corresponds to a pair excitation of energy $2\sqrt{(\epsilon_q - \mu)^2 + \Delta_0^2}$. Similarly, one obtains solutions with two and more excitations by choosing several signs e_j to be negative.

According to equations (4.15), the BCS and central spin models for $m = 1$ reduce to the following single spin models:

$$\tilde{H}_0 = -B\tilde{s}_0^z \quad \tilde{H}_{\text{BCS}} = -\frac{g}{2}\tilde{s}_0^+\tilde{s}_0^-. \quad (4.24)$$

Then, equation (4.13) provides an alternative parametrization of the residual spectral polynomial $\tilde{Q}_2(u)$

$$\tilde{Q}_2(u) = u^2 - \frac{2\tilde{s}_0^z}{\alpha}u + \frac{\tilde{s}_0^2}{\alpha^2}. \quad (4.25)$$

The solution of equations of motion is

$$J_-(t) = \tilde{s}_0^-(\vec{t}) = \alpha\Delta_0 e^{-i\beta t + i\phi} \quad (4.26)$$

where the frequency β is different for BCS (β_{BCS}) and central spin (β_0) models

$$\beta_{\text{BCS}} = 2\mu \quad \beta_0 = \frac{-e_0}{\sqrt{\mu^2 + \Delta_0^2}} \quad e_0 = \pm 1.$$

Components of original spins $\mathbf{s}_j(t) = 2\langle \hat{\mathbf{K}}_j(t) \rangle$ are given by equations (4.18) and (4.19). We have

$$s_j^-(t) = \frac{e_j J_-(t)}{\alpha \sqrt{(\epsilon_j - \mu)^2 + \Delta_0^2}} \quad s_j^z = -\frac{e_j(\epsilon_j - \mu)}{\sqrt{(\epsilon_j - \mu)^2 + \Delta_0^2}}. \quad (4.27)$$

Note that one-spin solutions constructed above do not minimize central spin Hamiltonian (2.9). Instead, we observe that in this case the configuration of spins with minimum energy is $s_j^z = -\text{sgn } \gamma_j$. Similarly, we see from equations (2.8) that configurations that minimize Hamiltonians H_q are $s_j^z = -\text{sgn}(\epsilon_q - \epsilon_j)$. Interestingly, according to the definition of pseudospins (2.2), one of these configurations is the unperturbed Fermi ground state. Since

all spins in these configurations are oriented along the z -axis, they are also stationary with respect to BCS Hamiltonian (2.6).

Two-spin solutions, $m = 2$. In this case there are two constraints (4.7) on four coefficients of a positively defined polynomial $\tilde{Q}_4(u)$.

$$\sum_{q=0}^{n-1} \frac{e_q}{\sqrt{\tilde{Q}_4(\epsilon_q)}} = 0 \quad \sum_{q=0}^{n-1} \frac{e_q \epsilon_q}{\sqrt{\tilde{Q}_4(\epsilon_q)}} = \alpha \quad e_q = \pm 1$$

$$\tilde{Q}_4(u) = \sum_{k=0}^4 \tilde{\alpha}_k u^k \quad \tilde{\alpha}_4 = 1.$$

Equations (4.9) and (4.12) show that the energy of these solutions can take arbitrary values in the range of energies allowed for the BCS and central spin models.

The equivalent two-spin problems (4.15) are

$$\tilde{H}_{\text{BCS}} = 2\tilde{\epsilon}_1 \tilde{s}_1^z - \frac{g}{2} \tilde{J}_+ \tilde{J}_- \quad \tilde{H}_0 = \frac{\tilde{\gamma}_0}{2} \tilde{\mathbf{s}}_0 \cdot \tilde{\mathbf{s}}_1 - B \tilde{s}_0^z. \tag{4.28}$$

We are left with only one separation variable $u_1 = \tilde{u}_1$ and equations (3.11) now read

$$\begin{aligned} \dot{u}_1^2 + 4\tilde{Q}_4(u_1) &= 0 && \text{BCS} \\ \tilde{\alpha}_0 \dot{u}_1^2 + \tilde{Q}_4(u_1) &= 0 && \text{central spin} \end{aligned} \tag{4.29}$$

while for the total (pseudo)spin, using equation (4.21), we obtain

$$\begin{aligned} \frac{d \ln J_-}{dt} &= \pm \frac{i}{\sqrt{\tilde{\alpha}_0}} u_1 && \text{central spin} \\ \frac{d \ln J_-}{dt} &= i\tilde{\alpha}_3 + 2iu_1 && \text{BCS.} \end{aligned} \tag{4.30}$$

Components of individual spins can be expressed either through u_1 and J_- or in terms of new spins using equations (4.20) and (4.18)

$$s_j^- = C_j J_-(\epsilon_j - u_1) = C_j(\epsilon_j - \tilde{\epsilon}_1) \tilde{s}_0^-(\tilde{t}) + C_j \epsilon_j \tilde{s}_1^-(\tilde{t}). \tag{4.31}$$

A special case of two-spin solutions when the four coefficients of a positively defined polynomial $\tilde{Q}_4(u)$ can be parametrized by three numbers, $\tilde{Q}_4(u) = ((u - \omega)^2 + \Delta_-^2 + \Delta_+^2)^2 - 4\Delta_-^2 \Delta_+^2$, has been previously discovered in [11]. The general two-spin solution is obtained from equations (4.29)–(4.31), which are solved by setting $n = 2$ ($g = 1$) in equations (3.17), (3.21) and (3.22) where hyperelliptic functions now become ordinary elliptic functions.

Similarly, one can obtain three, four etc spin solutions (degenerate solutions with $m = 3, 4$ etc frequencies) in terms of hyperelliptic functions of genus $g = 2, 3$, etc.

Degenerate solutions derived here are not all solutions with $m < n$ independent frequencies. Indeed, it is clear that for a generic point in the phase space all roots of the spectral polynomial $Q_{2n}(u)$ are distinct and, by continuity, the distance to the closest point where two roots coincide is finite. On the other hand, there are points with any number of frequencies arbitrarily close to any point in the phase space. Other solutions with $m < n$ frequencies can be constructed using the reduction theory for hyperelliptic functions [36].

Note also that degenerate solutions with m frequencies contain ones with fewer frequencies and can be further reduced to $m - 1, m - 2$, etc. Geometrically, they live on a $2m$ -dimensional surface in the $2n$ -dimensional phase space (see the remark below equation (4.21)). Surfaces with smaller m are embedded into ones with larger m . Interestingly, periodic trajectories that correspond to the BCS energy spectrum ($m = 1$) belong to all these surfaces.

5. Applications and open problems

Our results can be applied to the problem of decoherence within the central spin model. In this case, we believe, a complete exact answer can be obtained.

Another possible application is to experiments [2] on electron transport in spin blockaded semiconductor double dots. In this connection, it might be useful to analyse first a simpler setup of a single dot connected to two polarized leads. This setup leads [37] to an integrable model very similar to the central spin model.

Further, it might be possible to use the BCS model (2.6) with few classical spins to describe a number of grains connected to each other by Josephson junctions.

Other interesting applications include pairing phenomena in cold fermion gases [1] and in superconducting metals (see, e.g., the discussion in [29]). In these cases, a careful identification of observable robust features of the solution is needed.

An interesting open problem is the evaluation of leading finite size (quantum) corrections to the general solution obtained in this paper.

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